

Featureless: Bypassing Feature Extraction In Action Categorization

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What is Action Categorization?

Input Videos

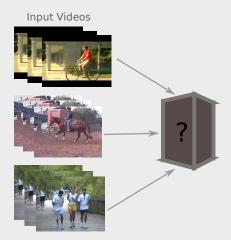






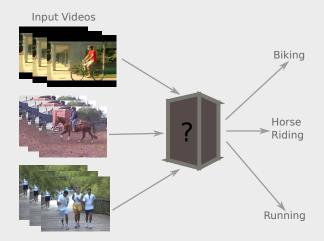
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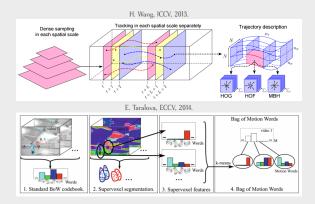


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Standard Classic Approaches

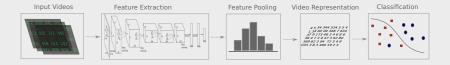


Variations of features over time:

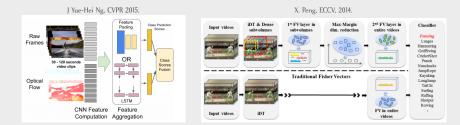


Problem: Feature extraction is slow and takes space to store.

Standard Deep Net Approaches



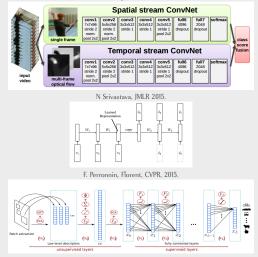
Variations of pooling over frames:



Problem: Still extracts features and aggregates them, but better features.

Deep Learning Approaches

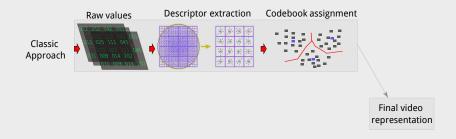
K Simonyan, NIPS 2014.



Slowly bridging the gap in performance.

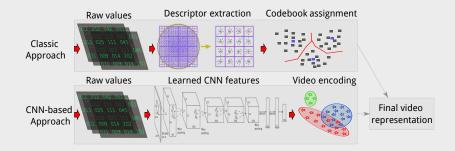
Is Feature Extraction Needed at Test-time?

• Classic: extract handcrafted features and use them in a video representation.



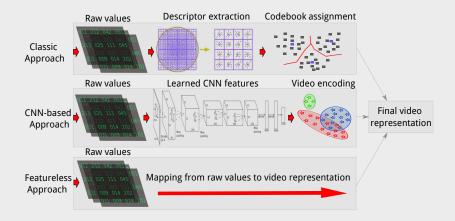
Is Feature Extraction Needed at Test-time?

• CNN-based: extract CNN features and use them in a video representation.



Is Feature Extraction Needed at Test-time?

• Featureless: predict codeword IDs and compute a first-order video representation.

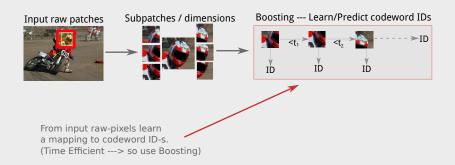


Proof of concept: discard the features and learn their statistics instead.

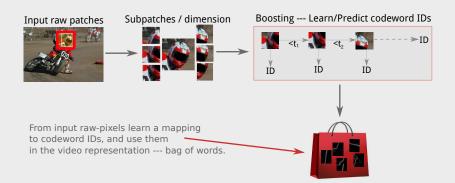


From input raw-pixel values.

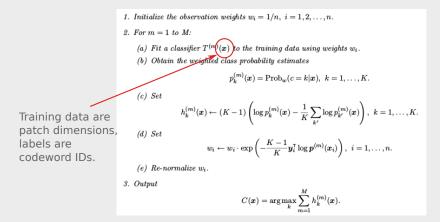
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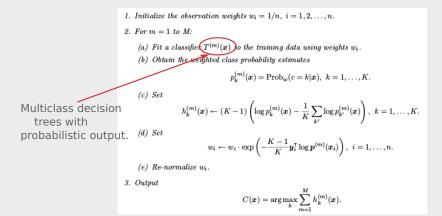
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- 1. Initialize the observation weights $w_i = 1/n, i = 1, 2, ..., n$.
- 2. For m = 1 to M:
 - (a) Fit a classifier T^(m)(x) to the training data using weights w_i.
 - (b) Obtain the weighted class probability estimates

$$p_k^{(m)}(x) = \text{Prob}_w(c = k | x), \ k = 1, ..., K.$$

(c) Set

 $h_k^{(m)}(\boldsymbol{x}) \leftarrow (K-1) \left(\log p_k^{(m)}(\boldsymbol{x}) \right) \frac{1}{K} \sum_{k'} \log p_{k'}^{(m)}(\boldsymbol{x}) \right), \ k = 1, \dots, K.$

weighted in each leaf by the sample (d) Set weight:

$$p_k^m(\mathbf{x}_i) = \frac{\sum_{i \in \mathcal{L}} w_i(y_i^k = 1)}{\sum_{i \in \mathcal{L}} w_i}$$

$$w_i \leftarrow w_i \cdot \exp\left(-\frac{K-1}{K} \boldsymbol{y}_i^{\mathsf{T}} \log \boldsymbol{p}^{(m)}(\boldsymbol{x}_i)\right), \ i = 1, \dots, n.$$

(e) Re-normalize w_i.

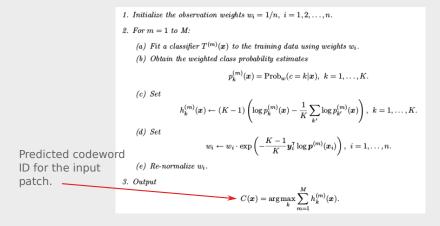
3. Output

$$C(x) = \arg \max_{k} \sum_{m=1}^{M} h_{k}^{(m)}(x).$$

We train the real version of the multiclass Adaboost [J. Zhu, 2009]:

1. Initialize the observation weights $w_i = 1/n, i = 1, 2, ..., n$. 2. For m = 1 to M: (a) Fit a classifier $T^{(m)}(\mathbf{x})$ to the training data using weights w_i . (b) Obtain the weighted class probability estimates $p_{k}^{(m)}(x) = \operatorname{Prob}_{w}(c = k | x), \ k = 1, \dots, K.$ (c) Set $h_k^{(m)}(\boldsymbol{x}) \leftarrow (K-1) \left(\log p_k^{(m)}(\boldsymbol{x}) - \frac{1}{K} \sum_{i \neq j} \log p_{k'}^{(m)}(\boldsymbol{x}) \right), \ k = 1, \dots, K.$ (d) Set \rightarrow $w_i \leftarrow w_i \cdot \exp \left(-\frac{K-1}{K}y_i^T \log p^{(m)}(x_i)\right), i = 1, ..., n.$ Weight updates. (e) Re-normalize w_i. 3. Output $C(\boldsymbol{x}) = \arg \max_{k} \sum_{m=1}^{M} h_{k}^{(m)}(\boldsymbol{x}).$

We train the real version of the multiclass Adaboost [J. Zhu, 2009]:

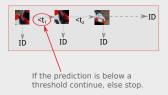


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- Early stopping Waldboost [J. Sochman, CVPR, 2005].

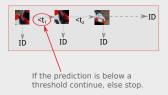


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- But Waldboost finds stopping thresholds for 2-class Adaboost only.
- Train on unused training data a stopping decision tree that gets as input the prediction of the strong classifier up to now.

$$\max_{k} \left(\operatorname{Stop}_{k}^{M'} \left(\sum_{q=1}^{m' \leq M} s_{k}^{m}(\bar{\mathbf{x}}_{i}) \right) \right) \geq \alpha$$

The strong classifier prediction up to M.

• Get a set of training videos and test videos.







During:

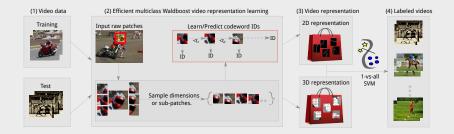
- training: extract (patch, codeword-ID) pairs;
- testing: only patches and predict codeword-IDs in the multiclass Waldboost.



• Compute a video representation with the predicted codeword-IDs.



• Use the video representation for action categorization.



Experimental Setup:

- ▶ UCF11 dataset. [J. Liu, CVPR, 2009]
- ► Codebook with K-means over 100 K descriptors.
- ► Gray-scale patches of 24*x*24 dimensions.
- ▶ 1000 weak classifiers, trained on 24 random dimensions.
- Stopping threshold α set to .97.

Waldboost word prediction versus other learning algorithms

► Setup:

- ▶ 100 dimensional codebook.
- ► HOG descriptors for codebook construction.
- ► Results:

	Linear SVM	Adaboost	Waldboost
MAP	16%	41%	41%
Time/frame	15.00 sec	4.00 sec	0.60 sec

Learning versus feature extraction

- ► Setup:
 - ▶ 100 dimensional codebook for HOG, HOF.
 - ▶ 1000 dimensional codebook for 3*D*-HOF.
 - ► 3*D*-HOG descriptors over 8 frames.
- Results:

	HOG		HOF	
	BOW	Waldboost	BOW	Waldboost
MAP	44%	41%	37%	32%

3D HOF				
BOW	Waldboost	BOW & Waldboost		
45%	36%	50%		

Learning featureless and codebookless representations

- ► Setup:
 - ▶ From the 100 K patches each is considered to be a data center.
 - Only \approx 100 patches have test-time patches assigned to them.
- Results:

	BOW	Codebookless	
		Adaboost	Waldboost
MAP	44%	41%	37%

Conclusions

- Present a proof of concept showing that we can bypass feature extraction.
- ► Still obtain comparable performance with the representation we learn from.
- ▶ To this end, a straightforward Waldboost multiclass approach is proposed.
- ► Finally, we consider both featureless and codebookless representations.

Thank you

